Amendments to the Claims

This listing of claim will replace all prior versions and listings of claim in the application.

1. (Currently Amended) A microstructure, comprising:

a first finger including a length, a first surface and a second surface, said first finger capable

of supporting a voltage potential between said first and second surfaces; and

a second finger including a first surface, said second finger capable of moving with respect to

said first finger between said first and second surfaces of said first finger upon application of a

voltage to said second finger,

wherein said first surface of said first finger is coplanar with said first surface of said second

finger in an unbiased position.

2. (Original) A microstructure as recited in claim 1, further comprising a first voltage source for

supplying a voltage to said first surface of said first finger.

3. (Original) A microstructure as recited in claim 2, further comprising a second voltage source

for supplying a voltage to said second surface of said first finger.

4. (Original) A microstructure as recited in claim 3, further comprising a third voltage source

for supplying a voltage to said second finger.

5. (Original) A microstructure as recited in claim 4, wherein the magnitude of said voltage

supplied by said third voltage source is significantly greater than said voltage supplied by said first

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and second voltage sources.

6. (Original) A microstructure as recited in claim 4, wherein the magnitude of said voltage

supplied by said third voltage source is at least ten times greater than said voltage supplied by said

first and second voltage sources.

7. (Original) A microstructure as recited in claim 4, wherein said microstructure effects a force

transducer upon said first finger.

8. (Original) A microstructure as recited in claim 4, wherein said microstructure effects a force

transducer upon said second finger.

9. (Original) A microstructure as recited in claim 1, said microstructure further comprising an

output, said output connected to an opamp circuit having an output, wherein said opamp circuit

output provides a signal representative of the relative position between said first and second fingers.

10. (Currently Amended) A microactuator formed on a substantially planar substrate capable

generating an electrostatic force in a direction substantially perpendicular to said substrate, said

microactuator comprising:

a stationary comb-finger including a top portion relatively distal from the substrate

and a bottom portion relatively proximal to the substrate, said stationary comb-finger capable

of supporting a voltage potential between said top and bottom portions; and

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a movable comb-finger capable of moving with respect to said stationary comb-finger

between said top and bottom portions upon application of a voltage to said movable comb-

finger;

the microactuator formed by the steps of:

(a) forming the stationary comb-finger by etching down through a top layer on

the substrate, the top layer being the uppermost layer on the substrate; and

(b) forming the movable comb-finger adjacent to the stationary comb-finger

formed in said step (a), the movable comb-finger formed by etching down through the top

layer on the substrate, the top layer still being the uppermost layer on the substrate.

11. (Original) A microactuator as recited in claim 10, further comprising at least a first voltage

source coupled between said top and bottom portions of said stationary finger, and a second voltage

source coupled to said movable finger.

12. (Original) A microactuator as recited in claim 11, wherein the magnitude of said voltage

supplied by said second voltage source is significantly greater than said voltage supplied by said at

least first voltage source.

13. (Original) A microactuator as recited in claim 11, wherein said voltage supplied by said

second voltage source is approximately 100 volts and said voltage supplied by said at least first

voltage source is approximately 10 volts.

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14. (Original) A comb-finger microactuator as recited in claim 10, a dimension of said stationary

finger in a direction perpendicular to the substrate being greater than a dimension of said movable

finger in a direction perpendicular to the substrate.

15. (Original) A microactuator as recited in claim 10, a dimension of said stationary finger in a

direction perpendicular to the substrate being at least one and one-half times greater than a dimension

of said movable finger in a direction perpendicular to the substrate.

16-26. (Withdrawn)

27. (Currently Amended) An assembly for an optical switching array micromachined in a

substrate, the assembly comprising:

a mirror for reflecting a signal to one of at least a first and second positions;

a spring member affixed to said mirror for flexibly anchoring said mirror over said substrate;

a microactuator for moving said mirror between said at least first and second position, said

microactuator including:

a stationary comb-finger having a top portion relatively distal from the substrate and a

bottom portion relatively proximal to the substrate, said stationary comb-finger capable of

supporting a voltage potential between said top and bottom portions; and

a movable comb-finger attached to said mirror, said movable comb-finger and said

mirror moving with respect to said substrate in a direction substantially perpendicular to said

substrate upon application of a voltage to said movable comb-finger and said stationary

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comb-finger

the microactuator formed by the steps of:

(a) forming the stationary comb-finger by etching down through a top layer on

the substrate, the top layer being the uppermost layer on the substrate; and

(b) forming the movable comb-finger adjacent to the stationary comb-finger

formed in said step (a), the movable comb-finger formed by etching down through the top

layer on the substrate, the top layer still being the uppermost layer on the substrate.

28. (Canceled)

29. (Original) An assembly for an optical switching array as recited in claim 27, further including

a second set of movable and stationary fingers wherein said second set of movable and stationary

fingers are offset approximately 90° from the first set of movable and stationary fingers.

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